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| **Task** | **Notes** | **Status** |
| Model robots |  | 100% DONE |
| Environment | Needs more safety stuff | 80%. |
| Gripper | NEEDS PINCING ANIMATION | 90% |
| RMRC + moving arm + moving chess piece | Can move the end effector from location x to y but chess piece does not follow end effector. | 50% |
| **E-stop (no uiwait)** | This needs to be priority. We will get bonus marks if we don’t have one. | 0% |
| GUI | This can come a bit later. Maybe make a GUI for robot.model.teach? | 0% |
| Collision detection | Week 5 lab | 0%. |
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